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JAKA



JAKA MiniCobo Collaborative Robot

Education Industry

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Shanghai JAKA Robotics Ltd

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Company Introduction



JAKA Robotics Co-founded by engineers and roboticists

We understand that the pursuit of excellence requires searching high and low, far and wide, for new ideas and innovation. We named ourselves 'JAKA', which stands for Just Always Keep Amazing, in appreciation for our strive towards excellence.

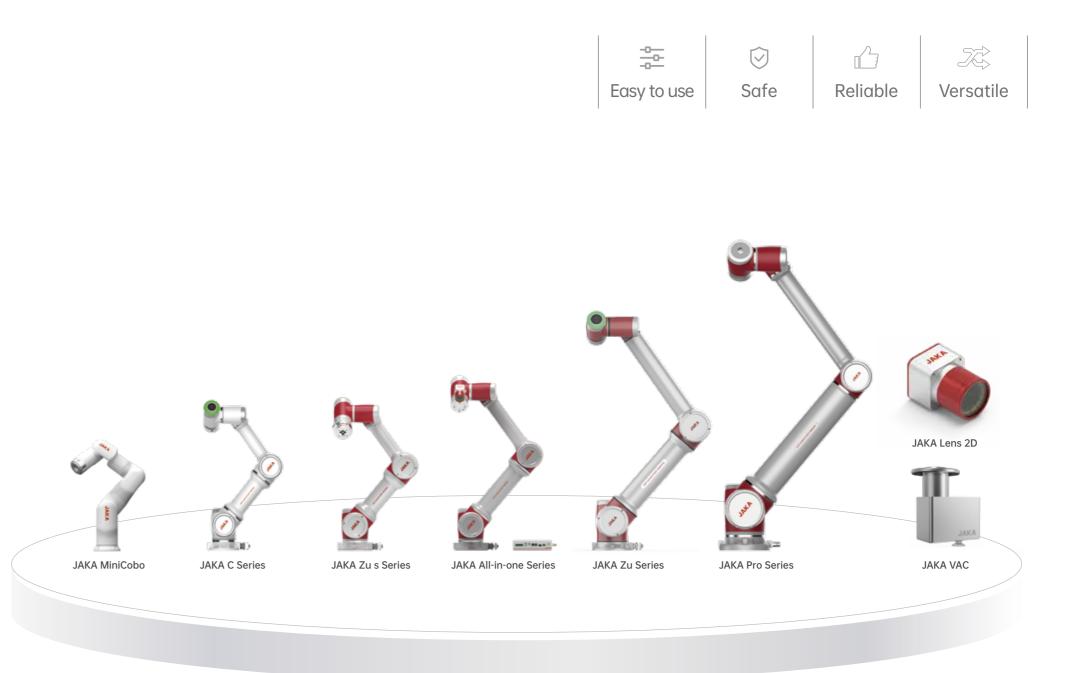
JAKA Robotics is a high-tech company that focuses on innovative research, development and production of new generations of collaborative robots. It stands at the forefront of creating truly smart factories, meeting the requirements of industrial robotics while maintaining high levels of useability and simplicity. Our moto, 'Free Your Hands by JAKA', represents our drive to help companies, all over the world, automate all manner of tasks.

So far, JAKA has worked with more than 300 companies, from all over the world, across multiple industries, to provide automation solutions. In total, more than 10,000 JAKA cobots have already been deployed. Their flexibility and efficiency help those in the automobile, electronics and semi-conductor manufacturing industries, while their ease-of-use has made them accessible to those in education, commerce and new retail industries.



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Global leader in flexible, intelligent cobots Ushering in a new generation in automation productivity





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JAKA MiniCobo

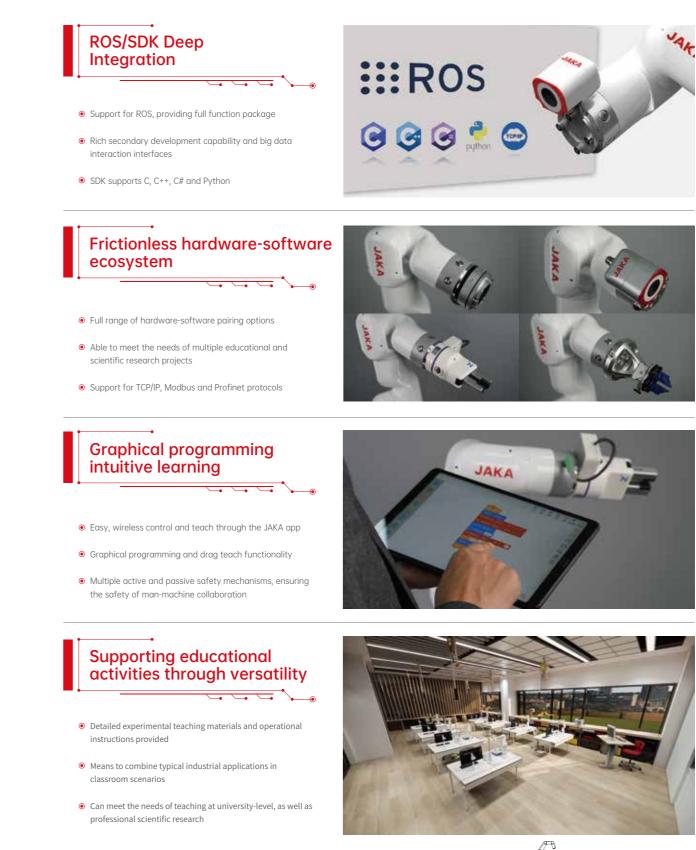
Developing a technological ecosystem of depth, with experiment-led development



The JAKA Minicobo is compatible with Ethernet protocols (TCP/IP) and control interfaces such as Modbus and Profinet. It can simply and quickly integrate end effectors, grippers, suction, vision systems and force control modules. JAKA also provides an ROS package and SDK secondary development package, meaning that operators can quickly adapt the cobot to suit new or experimental applications.







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JAKA 'Stars Program'

The JAKA 'Stars Program' was launched to cultivate talented individuals in robotics, artificial intelligence, intelligent manufacturing and other industries, in response to the national policy for the development of the robotics industry, in China's 14th Five Year Plan. The ng platform of the Stars Program places the JAKA Minicobo at its core, and through the configuration of vision, end effector, force control sensor, mental scenarios, it introduces three educational projects. By sharing JAKA' s considerable body of knowledge, hard technology capabilities and product support, JAKA seeks to integrate teaching and practice, thereby empowering the talents of the future.







'New Engineering' Construction

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Based on an experimental teaching platform, the Stars Program focuses on typical application scenarios. As a platform, it has the advantages of being accessible, secure and open, while transferring skills and knowledge that are widely compatible with 'New Engineering'

The Stars Program teaching platform can be combined with other hardware and technical avenues, in order to create innovative platforms involving, for example, artificial intelligence, voice interaction, face recognition, EMG signal reading and more.

Innovative Platform Development

	Category	Vision Project	Force Control Project	Collaborative Project
Robot	Cobot	\checkmark	\checkmark	\checkmark
Vision	2D Vision	\checkmark	\checkmark	\checkmark
Force Control	6-Axis Force Sensor		\checkmark	\checkmark
Vaccum Gripper	Suction Cup	\checkmark	\checkmark	\checkmark
Gripper	Electric Gripper	\checkmark	\checkmark	\checkmark
Mobile Platform	AGV/ARM			\checkmark
Other	Tablet	\checkmark	\checkmark	\checkmark
	Block Set	\checkmark	\checkmark	\checkmark
	TIO Special Cable	\checkmark	\checkmark	\checkmark





Size, colour & shape classification Bar code scanning, defect detection Assembly

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Competitions and Experimental Practice

The Stars Project combines typical industrial applications with teaching, developing practical skills as an integrated part of educational practice. At the same time, the teaching platform explores a rich interaction between software and hardware, so as to meet the needs of both teachers and students, and their independent experimental practice or pedagogy.

The versatile and wide-reaching software-hardware interactions that make up with Stars Program can inform the develop ment of additional curriculums. The theoretical knowledge and practice guidance are applicable in courses on robotics, machinery, electrical engineering, computer science and more.

Curriculum Development

Force detection Constant force Innovative applications



Moving

Intelligent picking Cross-scenario handling Innovative application



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Basic Cobot Teaching Platform

Vision System Development Platform

Platform Introduction The Basic Cobot Teaching Platform is composed of a JAKA Minicobo module, a basic function module, a vision module and a computer learning module. It aims to combine theoretical knowledge learning with basic function practice, to enable the quick mastery in applying robotics

knowledge. The platform is equipped with a complete curriculum, which can be applied in basic courses such as robot theory, machine vision, intelligent manufacturing and more.







Basic function module

Vision module

Platform advantages

- Operable via JAKA APP, with graphical and drag programming
- Combines theory with practice, to facilitate understanding and practical use skills
- Provides complete courses and routines, with best-practice examples, as access point for deeper robotics knowledge
- The integrated, customized design makes it perfect for use in a multimedia classroom
- Useable with any tablet, with a simple and intuitive operational interface

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Serial	Experiment
1	Robot cognition and assembly
2	Robot system settings
3	Basic robot operation
4	IO communication
5	Vision system and cognition
6	Vision system and communication
7	Parts sorting
8	Basic case study

Computer learning module



The Vision System Development Platform is composed of a JAKA Minicobo module, a vision system module, and an end gripper. It is supported with an array of learning components, a complete curriculum and experimental scenarios. As an experimental teaching platform, it is suitable for professional practical teaching of robotics, automation, electronics, applied computer science and more.

Platform Configuration Cobot module Vision system

Platform advantages

- Operable via JAKA APP, with graphical and drag programming
- Wireless connection, with no teaching pendant
- Equipped with collision detection, it supports six levels of collision
- Rich communication interfaces supporting a variety of end effecto in plug-and-play
- Supports C, C++, C#, Python and ROS
- Can quickly establish a new vision application, with the help of cold bar code recognition
- Capable of character recognition, measurement, calibration, alignment processing and more
- New scenarios can be quickly and easily established





	Serial	Experiment
	1	Safety operation procedures
	2	Collaborative robot cognition
	3	Use and control of teaching device
	4	Basic commands and position points
	5	IO point operations
	6	Vision system and cognition
	7	Industrial camera connection and calibration
ection	8	Edge contour extraction
	9	Bar code and QR code scanning
	10	LED lamp colour selection
	11	Dimension measurement of mechanical parts
	12	Vision system and communication
and	13	Hand-eye calibration
	14	Bottle cap positioning and sorting
t, image	15	Parts assembly
c,	16	Fixture design and adaptation
	17	Robot system integration

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Hybrid Cobot Development Platform

Platform Introduction

The Hybrid Cobot Development Platform combines the JAKA Minicobo with an AGV mobile platform. It is capable of simultaneous localization and mapping (SLAM), automatic navigation and obstacle avoidance. Equipped with a vision system, end effectors, force control sensors and more, it can complete experimental projects such as motion planning, visual grasping, and mobile material handling. It is an excellent educational and scientific research tool for robot technology, artificial intelligence, and intelligent manufacturing.

Platform Configuration

Cobot module

AGV module

Vision system (optional)

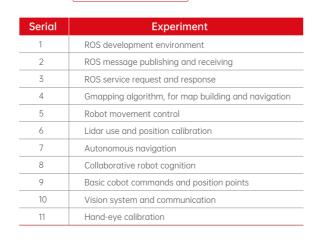
End effectors (optional)



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- Modular disassembly and assembly, adaptable according to appli cation, object, or experiment
- Wide variety of available end effectors
- Equipped with SLAM capability, automatic navigation, obstacle avoidance, three-dimensional mapping and more advanced technology
- Integrated software supports the control of multiple modules in the same software
- Supports C, C++, C#, Python and ROS

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Experiments







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Based on years of collecting industry application use cases, and project-matching them within the JAKA+ ecosystem, the JAKA Minicobo is able to offer a one-stop shop, a diverse solution for the education industry. It enables both theoretical and practical training, for use in laboratory construc tion, and the training of professional and technical personnel.











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Collaborative operation GB 11291.1-2011 standard Range of motion and speed						
24VDC						
M8						
Aluminium alloy, PC						
124mm						

Control cabinet				
Model	JAKA MiniCab			
Input power supply	20-60VDC			
Input current	<40A			
Size	180×128×47(mm)(L×W×H)			
IP level	IP20			
I/O port	7 ports, inputs and outputs configurable			
I/O power supply	24VDC			
Installation method	Installation method Panel / guide rail			
Communication standard	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP			
Weight	1.1kg			
Texture of material	Aluminium, steel			







Providing lifelong technical training Establishing a high-level training college especially for the robot industry

Online & offline flexible teaching

💀 Three training bases in Shanghai, Changzhou and Shenzhen Doline lecture halls





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